

Overview

The branch and bound problems

1 The branch and bound method for ILP problems

Branch and bound algorithms in general



The branch and bound method

The branch and bound method for IIP problems

- In today's lecture, we present another method for solving ILP problems. called the branch and bound method.
- We will solve an example and present the method at the same time.
- The computations needed are done with Matlab, and you can find the matlab script linearbranchandbound.m that were used on the course homepage.



The branch and bound method for IIP problems



The ILP problem that we will solve is

$$\begin{array}{ll} \textit{maximize} & z = 7x_1 + 3x_2, \\ \textit{subject to} \begin{cases} 2x_1 + 5x_2 \leq 30, \\ 8x_1 + 3x_2 \leq 48, \\ x_1, x_2 \geq 0 \textit{ integers.} \end{cases}$$

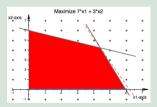
- Relax the problem by removing the integer constraints $x_1, x_2 \in \mathbb{Z}$.
- Introduce slack variables x_3 , x_4 and put the problem into canonical form:



The branch and bound method for II P problems

Example

maximize
$$z = 7x_1 + 3x_2$$
,
subject to
$$\begin{cases} 2x_1 + 5x_2 + x_3 = 30, \\ 8x_1 + 3x_2 + x_4 = 48, \\ x_1, \dots, x_4 \ge 0. \end{cases}$$



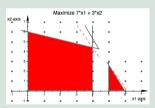


The first LP solution
Linear and Combinatorial Optimization

The branch and bound method for IIP problems

Example (Cont.)

- Solve using your file checkbasic1.m. We get the noninteger solution $x_1 \approx 4.41, x_2 \approx 4.23 \text{ and } z \approx 43.23.$
- Now the feasible set is split into two parts, $x_1 \le 4$ or $x_1 \ge 5$. x_1 is called a branch variable. The actual optimum of ILP must be in one of these subsets.



The optimum for ILP must be in one of the two subsets.

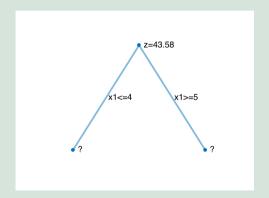


The branch and bound method for ILP problems

Branch and bound algorithms in general



■ We get a tree structure with the first LP problem at the stem of the tree.





The stem and the first two branches of the tree, one for each of the two subdomains.

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The stem and the first two branches of the tree, one for each of the two subdomains.

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The branch and bound method for IIP problems



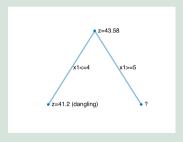
- We will solve the two new LP problems with the simplex method (using checkbasic1.m).
- We start with the left branch, and add the constraint $x_1 \le 4$ to the previous constraints, and start with the basic solution which was the optimum in the previous step.
- Note that this basic solution is not feasible now that the optimum is outside of the feasible set.
- We avoid the two phase method by using the dual as we did for the cutting plane method.



The branch and bound method for IIP problems

Example (Cont.)

- Using checkbasic1, we quickly find an optimum with optimal value 41.2.
- We leave this node for now (it is called a dangling node), and investigate the other branch corresponding to $x_1 > 5$.



We leave the dangling node for now and investigate the right branch.



The branch and bound method for IIP problems



- We replace the constraint $x_1 < 4$ with $x_1 > 5$, and obtain a new (infeasible) basic solution.
- Again, we solve the problem using the dual (with the script dualproblem.m.
- After a few iterations, we reach the optimal solution with z=43, which is noninteger since e.g. $x_2 \approx 2.6667$.
- Since 43 > 41.2, the right branch seems more promising than the left one, and we choose to continue with this branch.



The branch and bound method for IIP problems



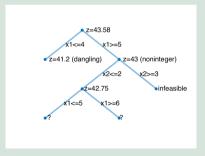
- We use x_2 as a branching variable, and split the problem into two cases: $x_2 < 2 \text{ or } x_2 > 3.$
- We start with the left branch, and solve using the dual problem. We get a noninteger optimum solution with z = 42.75 and $x_1 = 5.25$. This node is left as a dangling node.
- Next, we investigate the right branch, and so we replace the constraing $x_2 \le 2$ with $x_2 \ge 3$. This dual problem is unbounded, and so the primal problem is infeasible. There are no solutions in this branch.



The branch and bound method for IIP problems



Next, we go back to the dangling node corresponding to $x2 \le 2$. The optimal solution had $x_1 = 5.25$, and so we get two branches corresponding to $x_1 < 5$ and $x_1 > 6$, respectively.





The branch and bound method for IIP problems



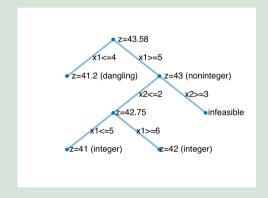
- Solving with the simplex method for the dual problem of the left branch, we get an integer optimal solution with z = 41. We still need to investigate the other branches.
- Doing the same for the right branch, we find an integer optimal solution with z = 42
- Compare the two integer optima that we have found and notice that z=42from the right branch has the highest value.
- There is another dangling node which we have to compare, but note that the LP optimum for that node was 41.2. and so the optimum for ILP in that branch cannot be higher than 41. Therefore, we don't need to investigate that branch any further.



The branch and bound method for II P problems



The final tree is shown in the figure below.



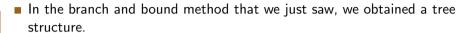


The final tree structure

Branch and bound algorithms in general

The branch and bound

Branch and bound algorithms in general



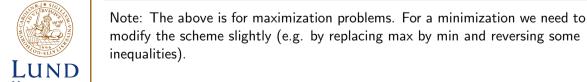
- We didn't need to explore all the branches of the tree.
- The simplex method gave an upper bound for the value of the ILP in each subset (each branch of the tree).
- When an integer optimum solution was found, we found an optimum value for the ILP problem for that branch.
- The simplex method was only needed for finding an upper bound in the subtrees (branches). If we have another way of getting such bounds, then the same idea can be used for other types of (discrete) optimization problems as well.
- Hence also nonlinear problems can be solved with branch and bound methods.



Branch and bound algorithms in general

What do we need?

- A procedure branch, which splits each subset D^k into smaller parts $D^{k,1}$ $D^{k,n}$
- A procedure bound, which for each subset D^k .
 - always finds an upper bound $f_{II}^k \ge \max_{\mathbf{x} \in D^k} f(\mathbf{x})$,
 - \blacksquare sometimes finds a lower bound $f_k^k < \max_{\mathbf{x} \in D^k} f(\mathbf{x})$,
 - sometimes finds the optimum $f_i^k = \max_{\mathbf{x} \in D^k} f(\mathbf{x})$





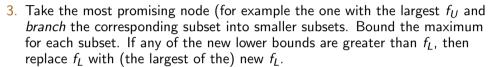
Branch and bound algorithms in general

Algorithm idea:

- Use the procedure bound to find upper and lower bounds for the whole problem.
- Save the node D together with its upper bound in a list $L = \{(D, f_U)\}.$ Keep a note of f_l if a lower bound was obtained. Otherwise, let $f_l = -\infty$.



Branch and bound algorithms in general



- If a node has $f_{II}^k \leq f_L$, then the optimum cannot be found in that subdomain. This branch can be cut off.
- If we find the optimum in a subdomain, then this domain need not be split any further. The branch ends here.
- 4. The nodes where an optimal solution is not found $f_L^k > f_L$ need to be examined further. Put them in a list and repeat from 2.



Branch and bound algorithms in general

- Note that in the ILP example, the simplex method was used to find the upper bounds.
- Lower bounds were only found in the case where there was an integer optimal solution of the subproblem.



The travelling salesman problem

problems

Branch and bound algorithms in general

Example (The travelling salesman problem)

- **A** Salesman has to visit n cities C_1, \ldots, C_n , starting from his home city C_1 and then visiting the other n-1 cities in some order and finally returning to his home city C_1 .
- Let c_{ii} be the distance between city i and j. In which order should he visit the cities in order to minimize the total distance?
- There are many different algorithms for this problem, but it is a known hard problem to solve if the number of n is large.



Branch and bound algorithms in general

Example (Travelling salesman problem, Cont.)

The problem can be formulated as an ILP problem using the variables

$$x_{ij} = egin{cases} 1 & \textit{if the salesman travels directly from} \\ & \textit{city i to city j the route,} \\ 0 & \textit{otherwise.} \end{cases}$$

as well as artificial variables u_i , i = 2, ..., n.

The artificial variables u; will prevent subcycles from forming, as we will soon see.



problems

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Example (Travelling salesman problem, Cont.)

The LP problem is

Branch and bound algorithms in general

Example (Travelling salesman, Cont.)

- The objective function is just the total length of the route.
- The first two constraints ensures that the salesman arrives at and leaves each city exactly once.
- The third constraint prevents subcycles from forming like in the figure below.





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problems

Branch and bound algorithms in general



- The problem can be solved as an ILP with the cutting plane method or branch and bound as last time or directly with a branch and bound algorithm without the simplex method as you will do in handin 2.
- It is hard to solve this in a reasonable time when the number of cities is large, and it will be interesting to see how big problems you can solve with your algorithm.



The branch and bound method for ILP problems

Branch and bound algorithms in general

Example (Travelling salesman problem, Cont.)

- In 2004, the travelling salesman problem for Sweden's towns was solved. The problem contains 24,978 towns. At the time, it was the largest TSP that had been solved. Read more about the project.
- The current record is an 85,900-city tour that arose in a chip-design application.





problems

Branch and bound algorithms in general



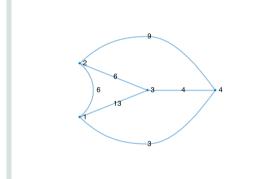
- In handin exercise 2, you will work on a branch and bound algorithm for the TSP problem.
- Note that TSP is a minimization problem, so the algorithm has to be constructed with this in mind.
- I will show you how the algorithm should work in a small example based on the data given on the next slide.



Travelling salesman as in handin 2

The branch and bound problems

Branch and bound algorithms in general



Example (Cont.)

The table contains min and max distances from each city (except 1) to some other city.

| | Min | Max |
|---|-----|-----|
| 2 | 6 | 9 |
| 3 | 4 | 13 |
| 4 | 3 | 9 |

TSP example



Travelling salesman as in handin 2

The branch and bound method for ILP problems

Branch and bound algorithms in general



- Start in city 1. There are three possibilities, depending on which city we choose as number 2. We get a tree structure.
- How to calculate upper (u.b.) and lower bounds (l.b.): If the salesman travels from city 1 to city 2, we get the following quick upper and lower bounds for the route length, based on the table on the previous page:

$$6 + \begin{cases} 6 + 4 + 3 = 19, \\ 9 + 13 + 9 = 37. \end{cases}$$



TSP as in handin 2

The branch and bound method for ILP problems

Branch and bound algorithms in general

Example (Cont.)

■ Likewise, if he travels to city 2 or city 3 from city 1, then we get the bounds

$$13 + \begin{cases} 6+4+3 = 26, \\ 9+13+9 = 44, \end{cases}$$
 and $3 + \begin{cases} 6+4+3 = 16, \\ 9+13+9 = 34, \end{cases}$ respectively.



Travelling salesman (Cont.)

problems

Branch and bound algorithms in general

Example (Cont.)

- From the lower bounds, we find that the node 1.4 looks most promising. and we need the other two nodes dangling.
- We branch the node 1,4 into the two nodes 1,4,2 and 1,4,3, for which the tour is known (since the fourth city has to be the 3 and 2, respectively). We get optimal values 31 and 19, respectively.
- See a figure of the tree structure on the next slide.

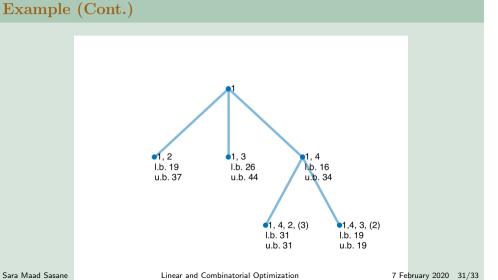


Travelling salesman (Cont.)

The branch and bound method for ILP problems

Branch and bound algorithms in general





Travelling salesman (Cont.)

The branch and bound method for ILP problems

Branch and bound algorithms in general

Example (Cont.)

- If we are content with finding one solution, we can cut the node 1,2 since the lower bound $19 \ge 19$ (the upper bound/optimum in a side branch). If we are looking for all solutions, we need to investigate this node further.
- We cut the note 1,3 and 1,4,2 since 26 > 19 and 31 > 19, respectively.



Branch and bound algorithms in general

Example (Cont.)

The final tree is shown below:

